

Sources:

- Arduino Hands-on Workshop, SITI, Universidad Lusófona
- Arduino Spooky projects
- Basic electronics, University Pennsylvania
- Beginning Arduino Programming
- Getting Started With Arduino

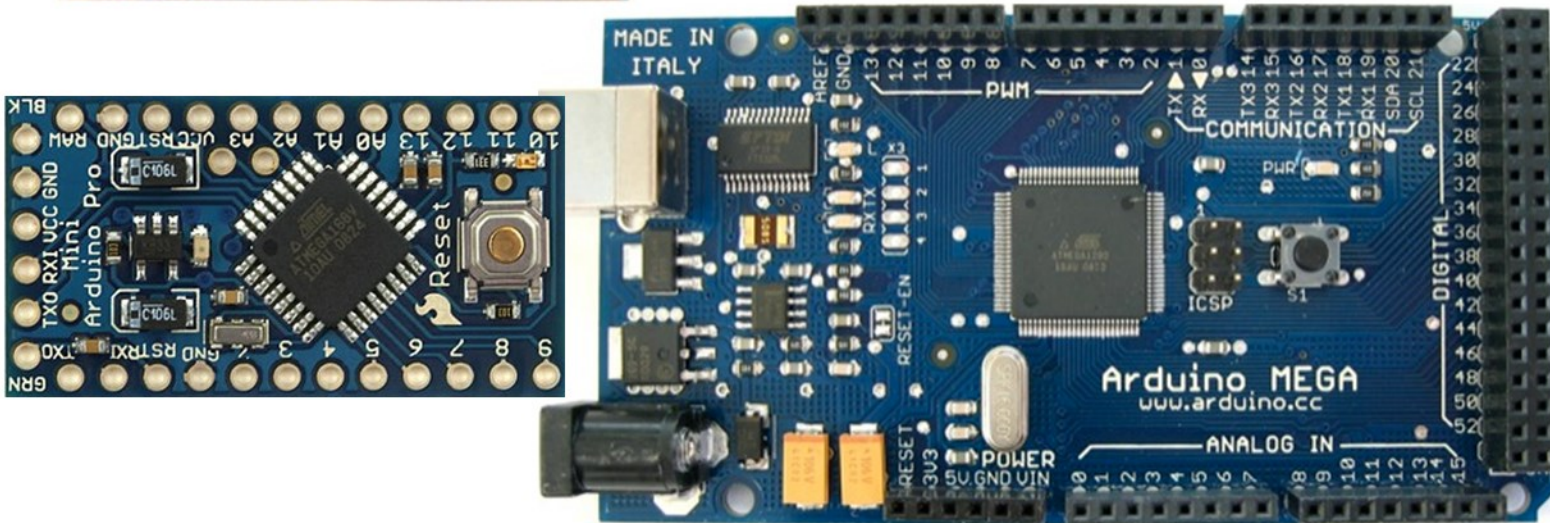
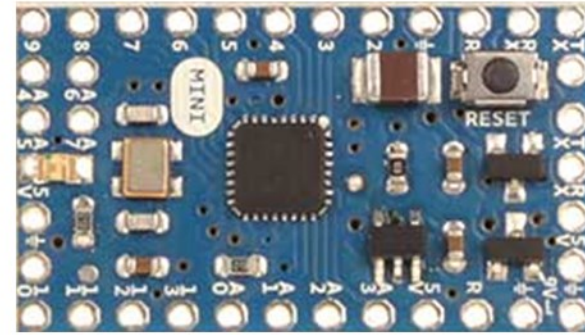
COURSE ON ADVANCED INTERACTION TECHNIQUES

PROGRAMMING ARDUINO

Luís Carrico

FCUL 2012/13

ARDUINO



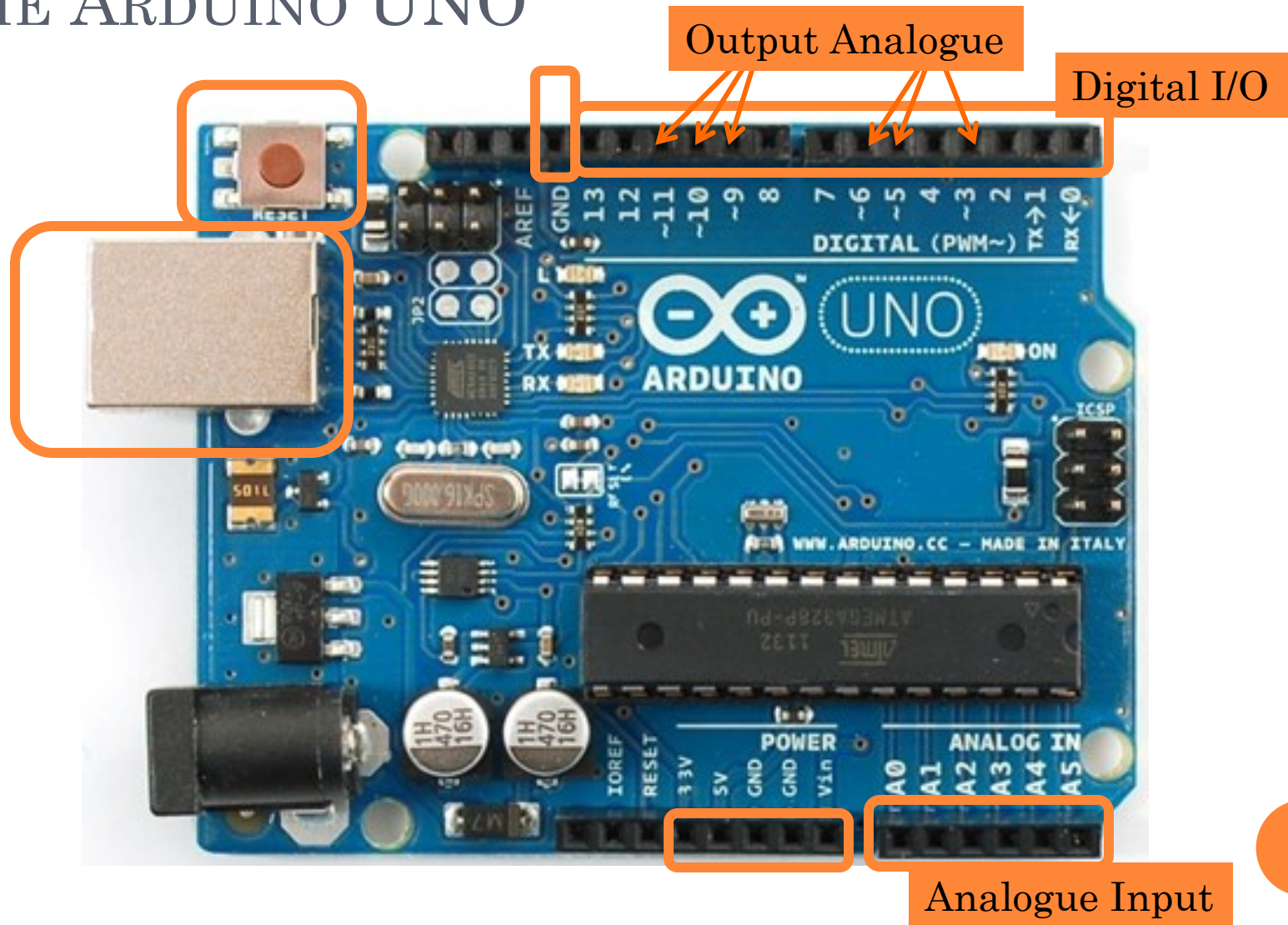
WHAT IS ARDUINO?

- “Arduino is an open-source physical computing platform based on a simple i/o board and a development environment that implements the Processing / Wiring language.
- Arduino can be used to develop stand-alone interactive objects or can be connected to software on your computer.“

○ www.arduino.cc, 2006



THE ARDUINO UNO

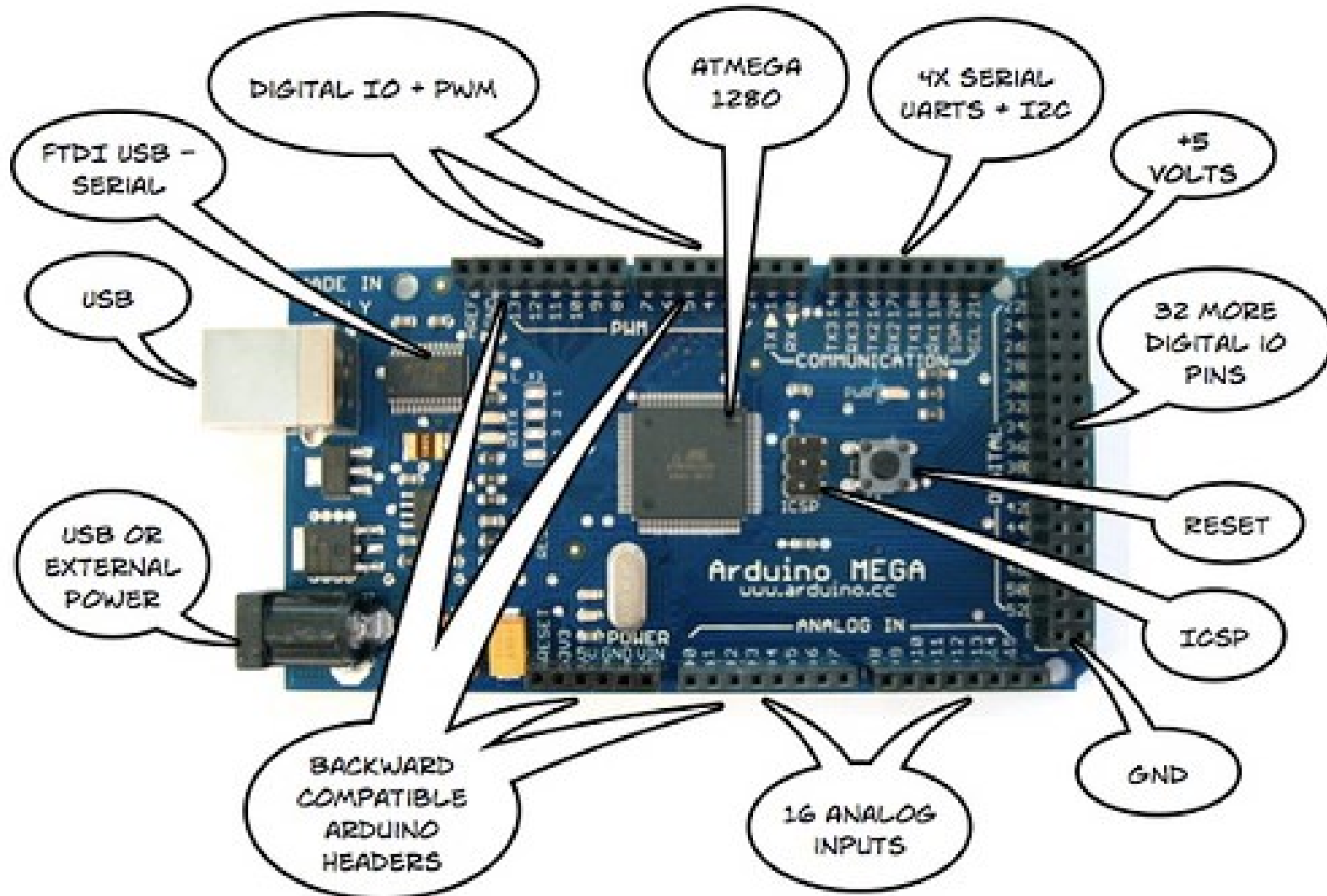


THE UNO

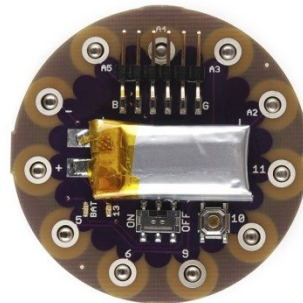
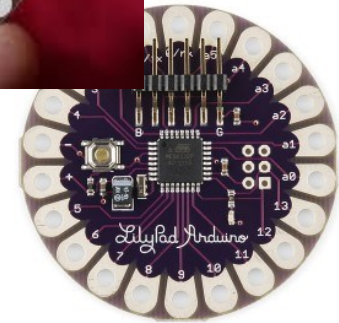
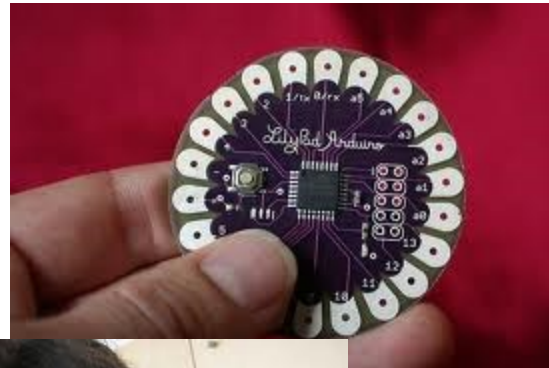
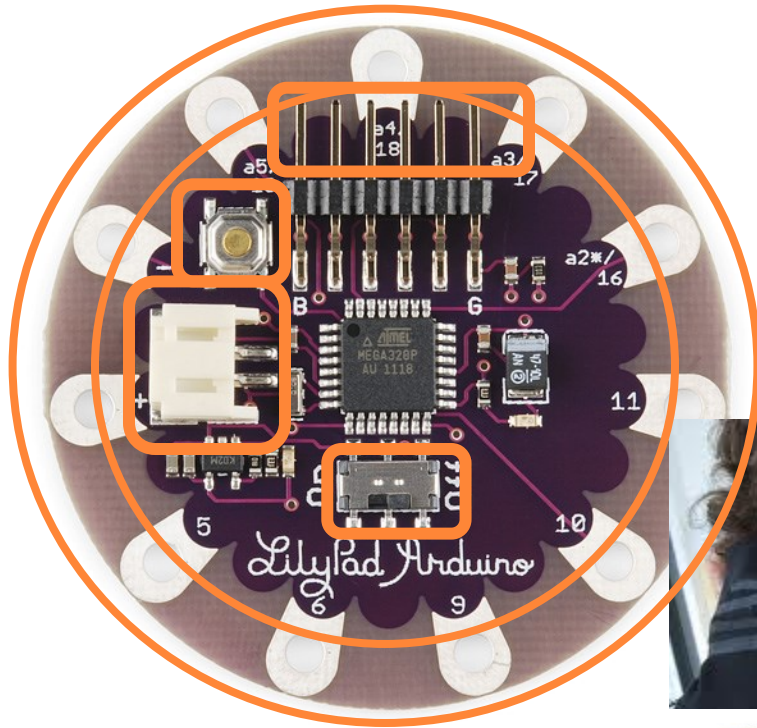
- 16 Kbytes of Flash program memory
- 1 Kbyte of RAM
- 16 MHz
- Inputs and outputs
 - 13 digital input/output pins
 - 5 analogue input pins
 - 6 analogue output pins (PWM only)



THE ARDUINO MEGA



THE LYLYPAD





ELECTRONICS

Basic Concepts

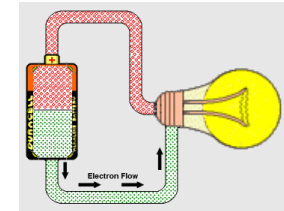
BASIC ELECTRONICS CONCEPTS

○ Voltage (V)

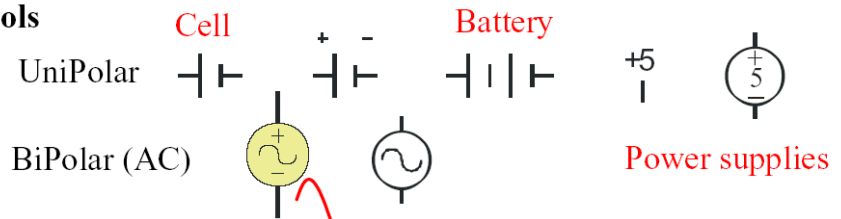
- electrical potential difference between two points;
- measured in volts

○ Current (I)

- intensity of electric current;
- measured in amps

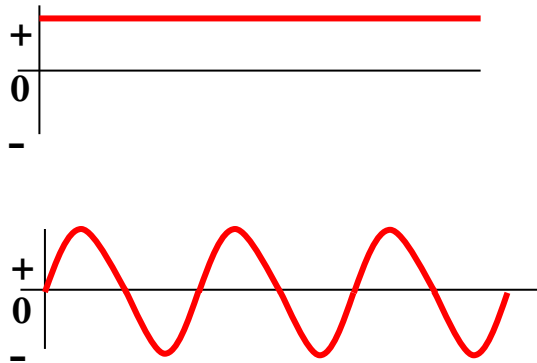


Symbols

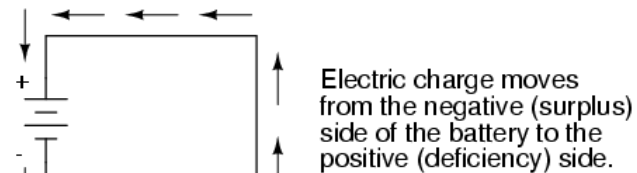


Properties

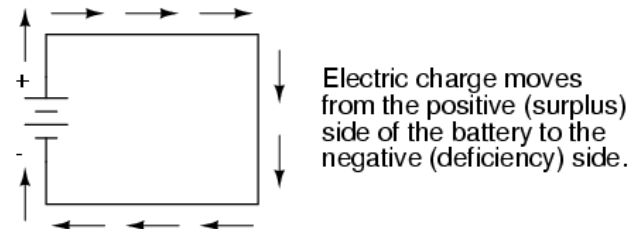
Constant Voltage, independent of the amount of current



Electron flow notation



Conventional flow notation



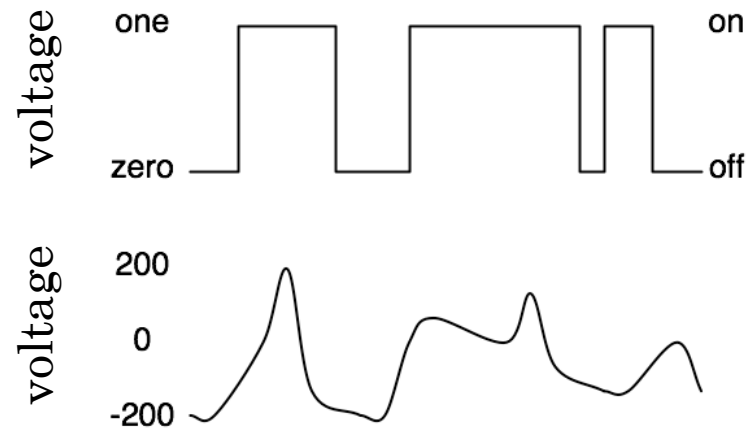
○ Voltage pushes, current flows



BASIC ELECTRONICS CONCEPTS

○ Digital/Analogue

- Digital is Boolean (on/off interpretation)
- Analogue is continuous



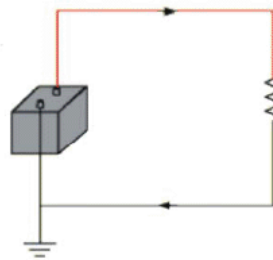
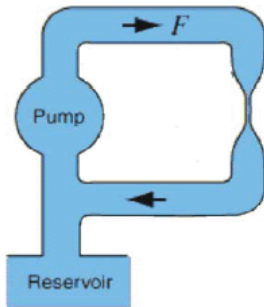
- Computers don't really do analog,
 - so they fake it, with quantization



BASIC ELECTRONICS CONCEPTS

○ Ground

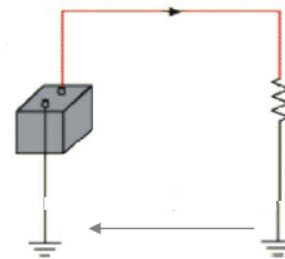
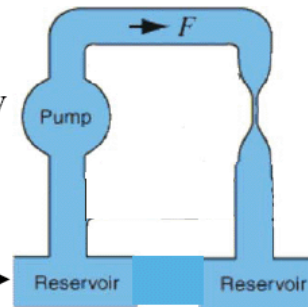
Provides a reference point



Purely a reference point

Does not participate in current flow

An integral path in the current flow



Symbols



Earth

Analog Gnd



BASIC ELECTRONICS CONCEPTS

○ Resistance

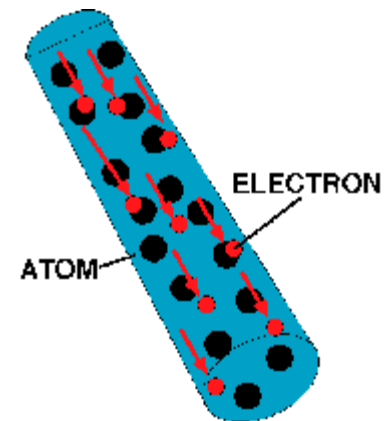
- All materials have a resistance that is dependent on cross-sectional area, material type and temperature

○ Ohms Law

$$V = RI$$

$$I = \frac{V}{R}$$

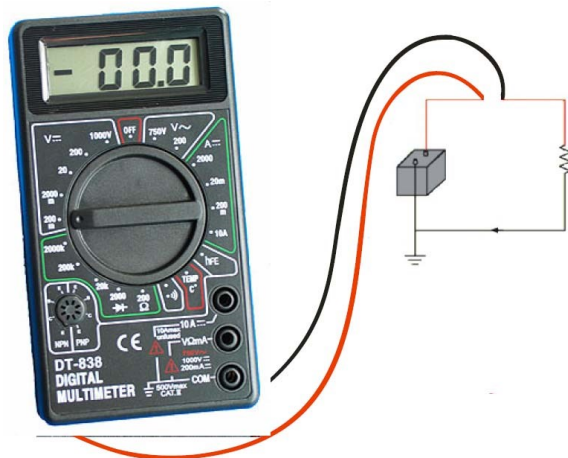
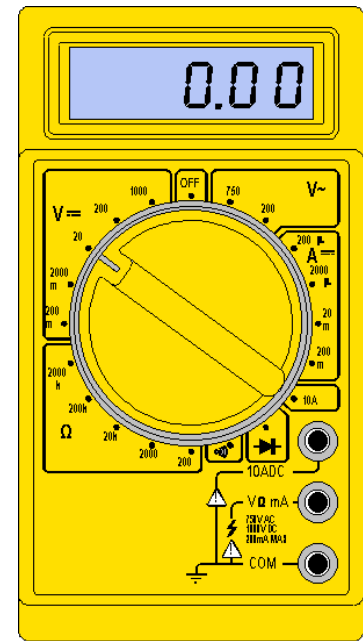
$$R = \frac{V}{I}$$



THE MULTIMETER

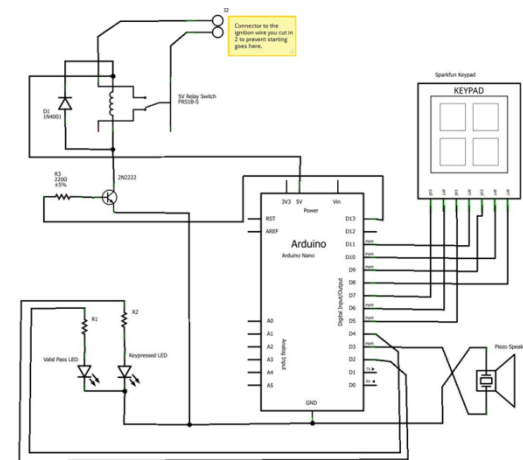
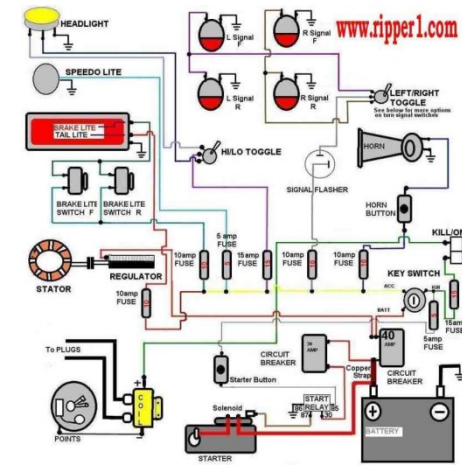
○ Types of meters

- Ammeter: measures current.
- Voltmeter: measures the potential difference (voltage) between two points.
- Ohmmeter measures resistance.
- Multimeter: combines these functions and others into a single instrument



DIAGRAMS

- Wiring drawing shows the interconnection (physical layout) of all devices and components
- Schematic drawing shows underlying logic may *not link back to physical layout*



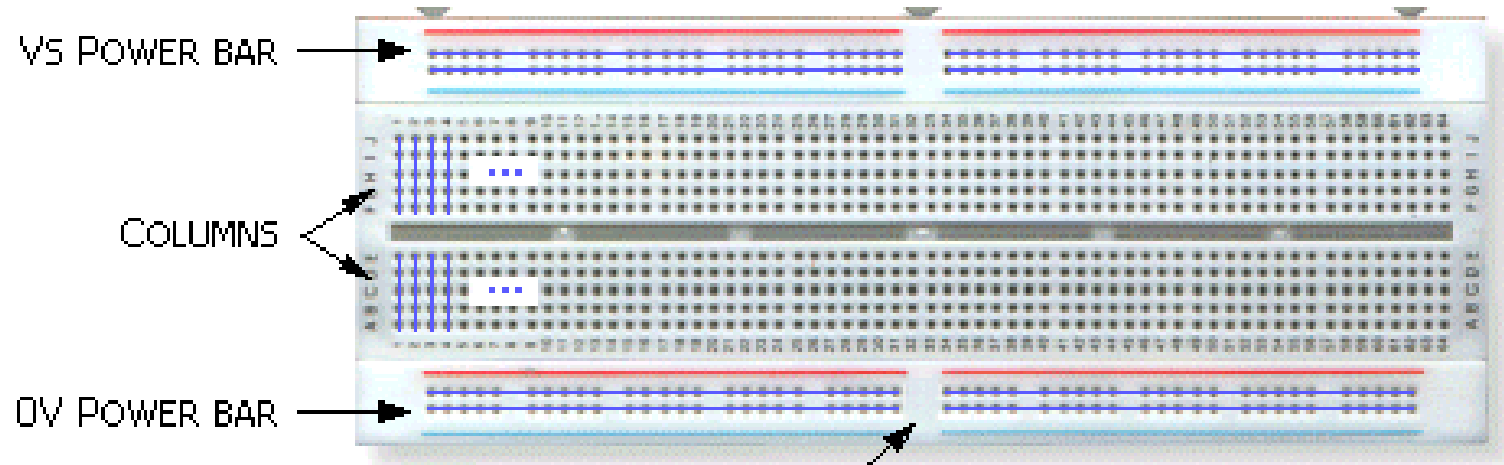


COMPONENTS & SHIELDS

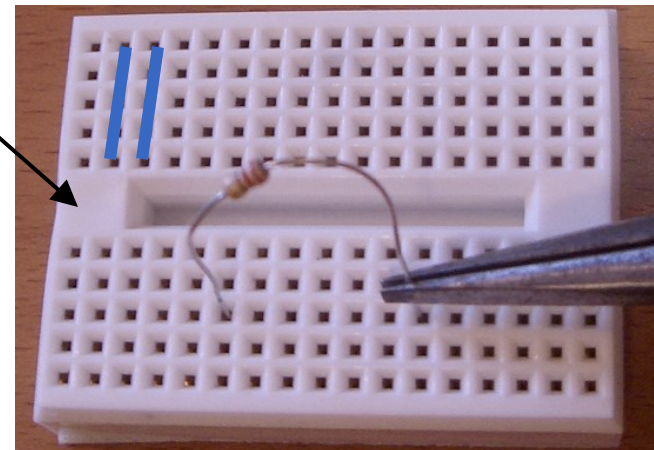
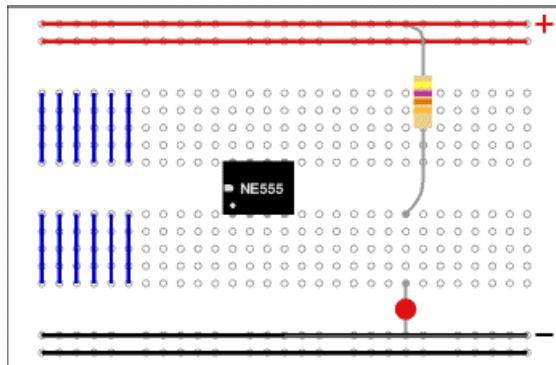
Common Components and Shields
For Arduino Projects

COMPONENTS: PROTOTYPING BOARD

- Used to connect components



NO CONNECTION HERE



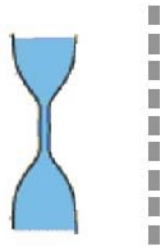
COMPONENTS: THE RESISTOR



○ Used to:

- limit the intensity of current flowing on a circuit
- transform electrical energy into heat

Constriction
creates
Resistance to water flow



Resistor creates
Resistance to current
flow

Symbols



3.3K Ω



Rare



2.7M

Variable resistor



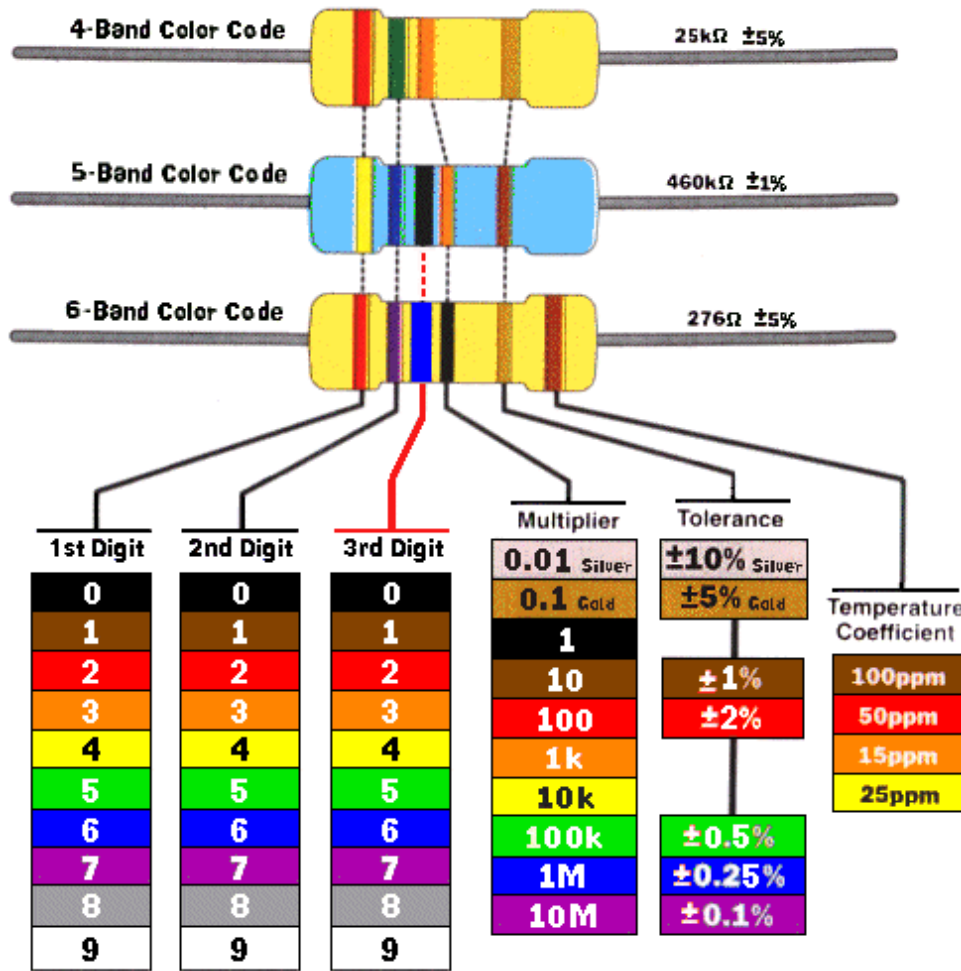
3K3

3.3k

○ Re...



COMPONENTS: THE RESISTOR



Important factors:

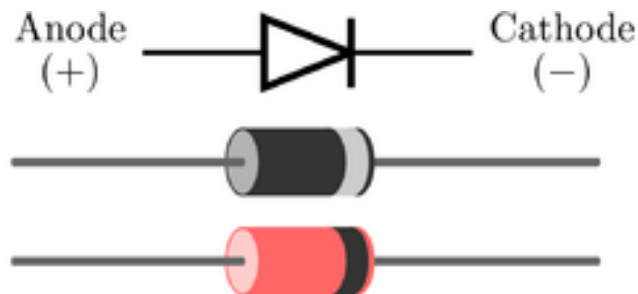
- tolerance of the nominal value and its stability considering the storage and operation conditions;
- the maximum power dissipated;
- the temperature coefficient;
- the maximum voltage in the terminals.



COMPONENTS: THE DIODE



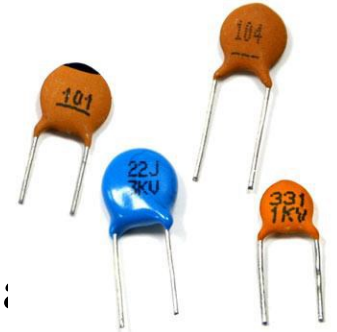
- Allows current to pass through in one direction more easily than the other
- Convert alternating current into direct current



- Important factors:
 - Forward voltage drop (V_f)
 - Peak Inverse Voltage (PIV)
 - Maximum forward current
 - Leakage current

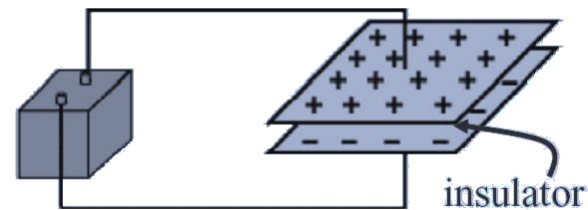


COMPONENTS: THE CAPACITOR

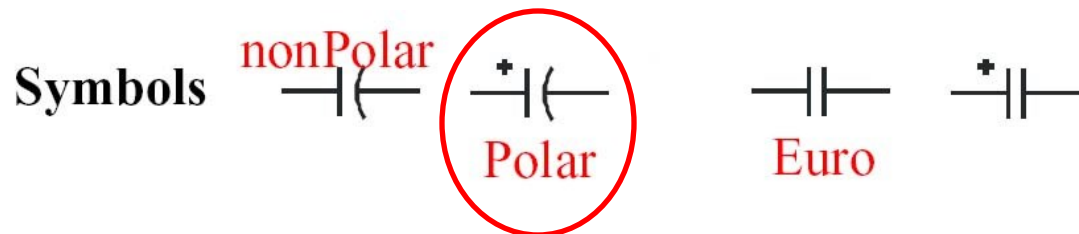


- Stores energy in an electric field, accumulating an internal imbalance of electric charge

Charge storage



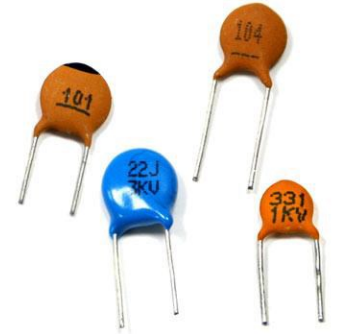
- Used to:
 - Stabilize voltage;
 - Noise filtering;
 - Separate AC DC (this is known as AC coupling).



- The storage capacity (C) is measured in farads (F).



COMPONENTS: THE CAPACITOR



○ Types

- ceramics (low values up to about 1 mF);
- polystyrene (usually in the range of picofarads);
- polyester (about 1 nF to 10 mF);
- polypropylene (low loss, high voltage, resistant to breakdown);
- tantalum (compact, low-voltage device, up to about 100 mF);
- electrolyte (high power, compact but lossy, in the range of 1 mF to 1000 mF);



Mylar



Monolythic
Cermamic



Tantalum



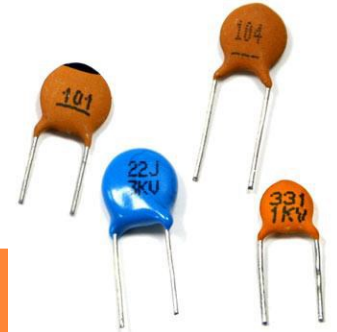
Ceramic



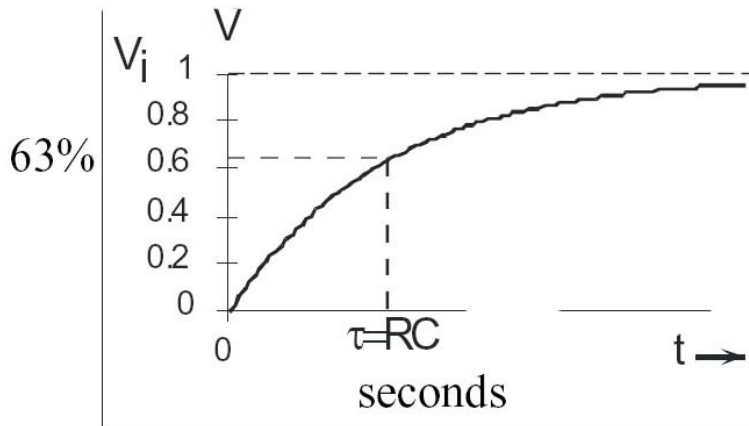
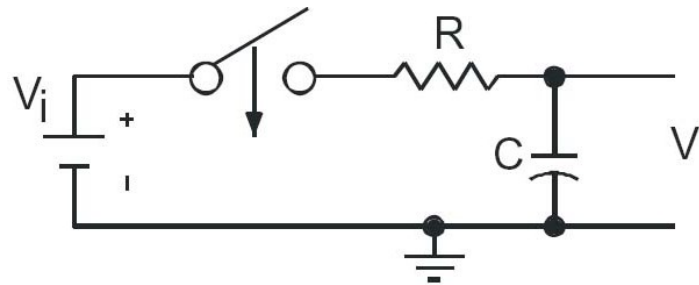
Electrolytic



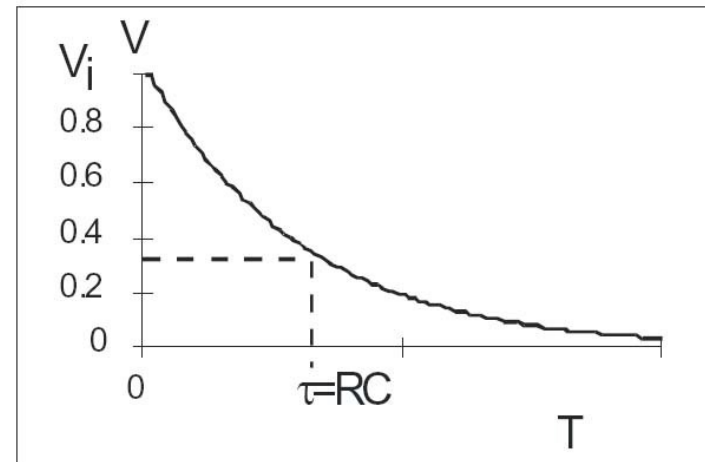
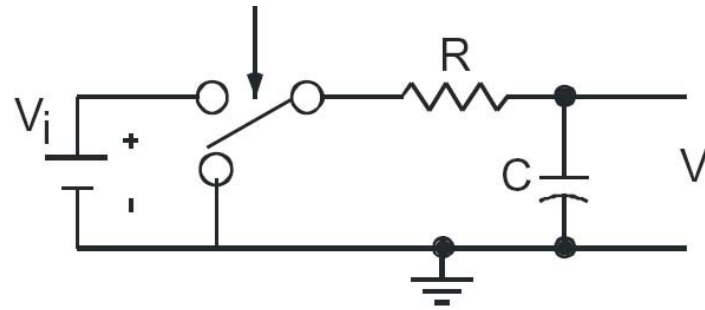
COMPONENTS: THE CAPACITOR



$$V = V_i - V_i e^{-t/RC}$$



$$V = V_i e^{-t/RC}$$

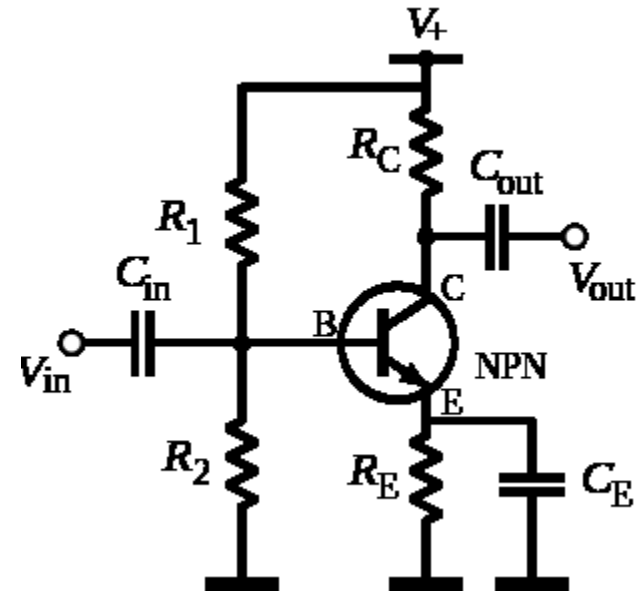
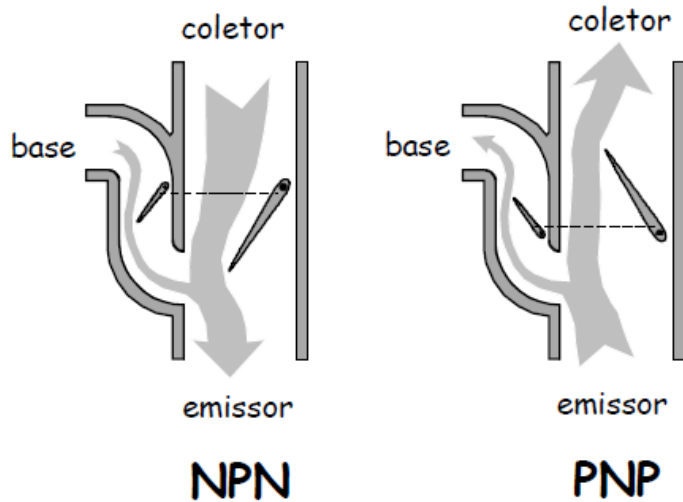


COMPONENTS: THE TRANSISTOR

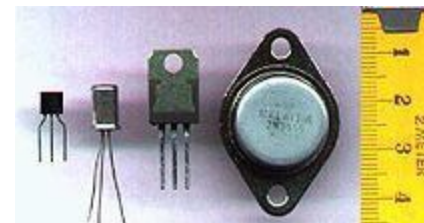


- Used as:

- amplifiers and switches for electrical signals.

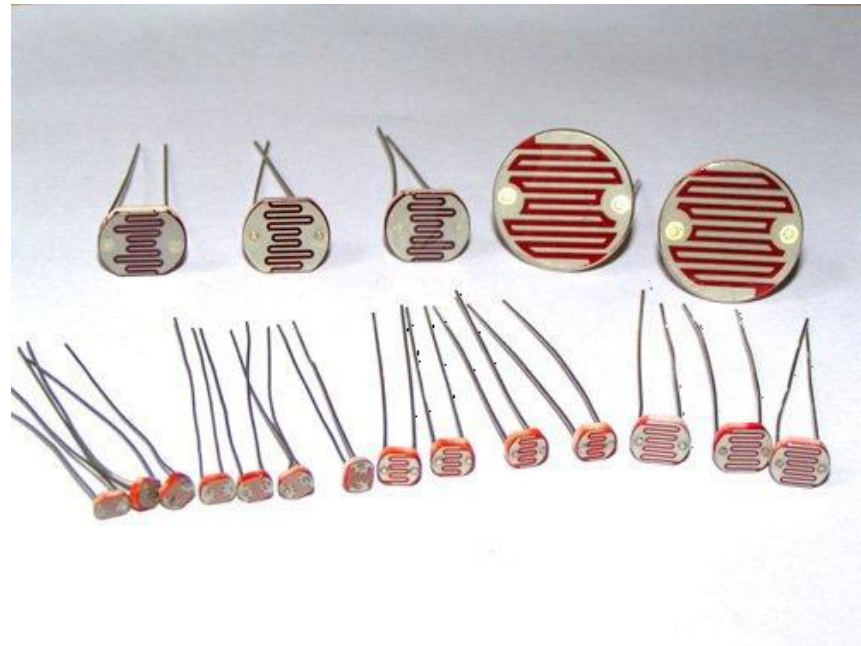
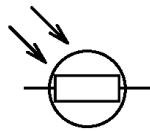
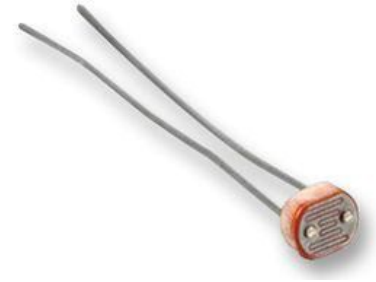


- Should find which pin is which!



COMPONENTS: THE LDR

- Light Dependent Resistor (LDR)
 - is a resistor whose resistance decreases with increasing incident light intensity. It can also be referred to as a photoconductor.



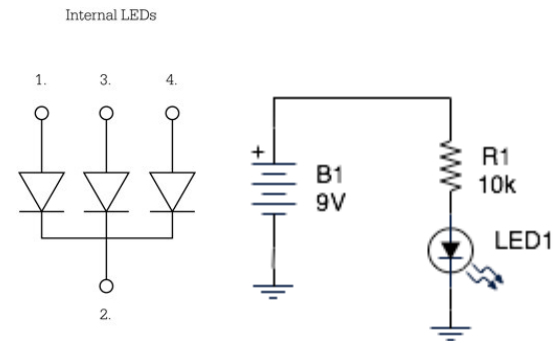
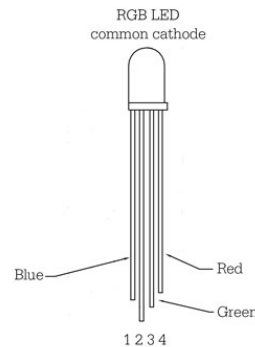
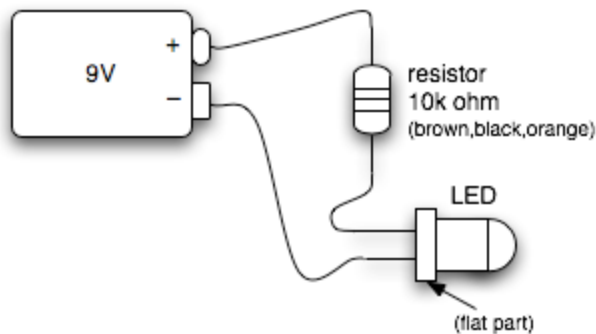
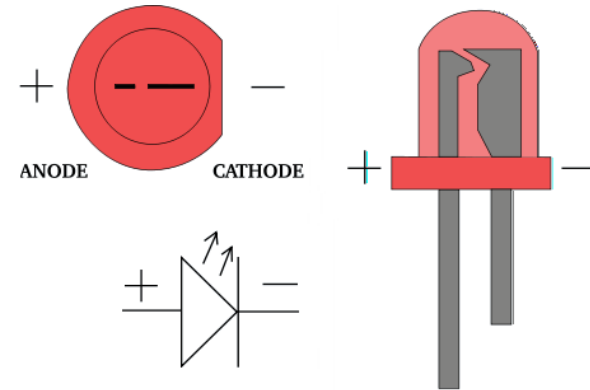
- http://en.wikipedia.org/wiki/Light_Dependent_Resistor



COMPONENTS: THE LED

- LED = Light-Emitting Diode

- it is a diode
- Emits light



- Important factors:

- Needs a “current limiting” resistor, or burns out



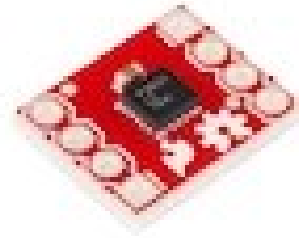
COMPONENTS: SENSORS



Vibration



Tilt



Accelerometer



Temperature



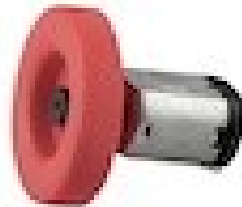
COMPONENTS: ACTUATORS & CONTROLLERS



Vibration



Buttons



Buzzer



Motor



Potenciometer



SHIELDS

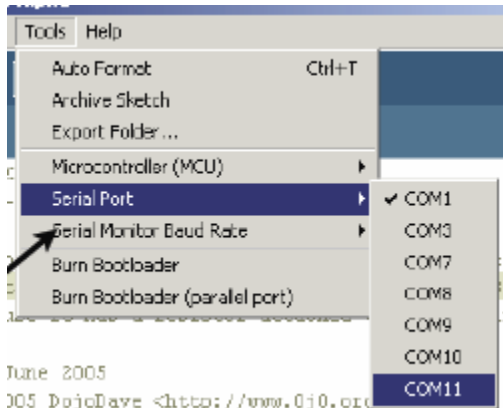
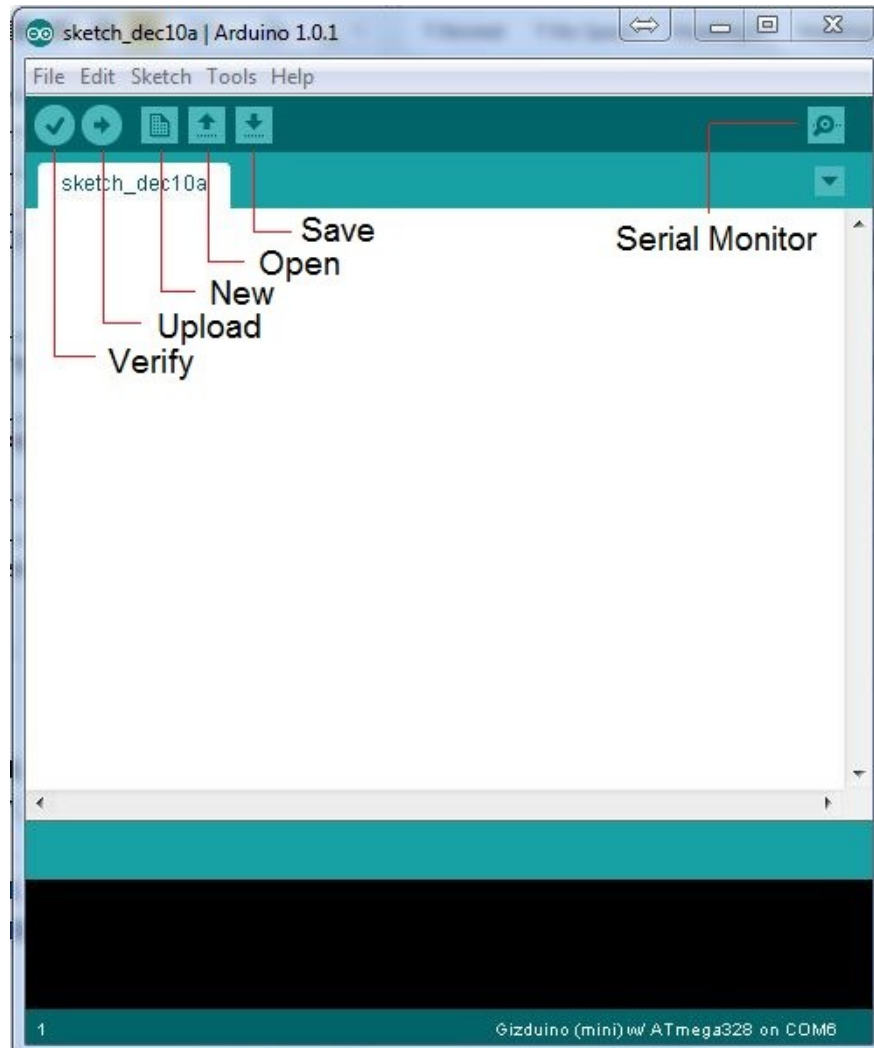




PROGRAMMING

Programming the Arduino

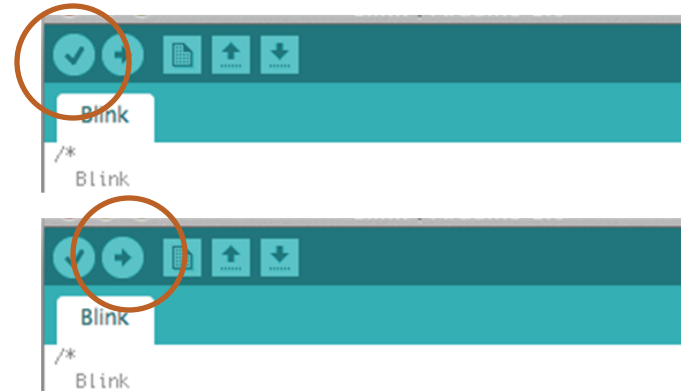
THE ARDUINO PLATFORM



SKECHING THE ARDUINO

- Write the “*sketch*” - program that runs on the board
- Check it
- Upload it
- It's running – may reset

```
void setup() {  
  // initialize the digital pin as an output.  
  // Pin 13 has an LED connected on most Arduino boards:  
  pinMode(13, OUTPUT);  
}  
  
void loop() {  
  digitalWrite(13, HIGH); // set the LED on  
  delay(1000);           // wait for a second  
  digitalWrite(13, LOW); // set the LED off  
  delay(1000);           // wait for a second  
}
```



NA ARDUINO SKETCH



- Declare at the top
 - variables and constants
- Initialize
 - setup()
 - run once at beginning, set pins
- Running
 - loop()
 - run repeatedly



NA ARDUINO SKETCH - DECLARE

```
// led connected to control pin 13
```

```
int ledPin = 13;
```

```
// setup sensor 'aSensor' on analog pin 0
```

```
int aSensor = 0;
```

```
// use this to hold the state of a pin
```

```
int statePin = LOW;
```

- Constants
 - LOW, HIGH
 - INPUT, OUTPUT
 - ...
- Types
 - boolean, byte, int unsigned, ... float, ...
 - Arrays [] with {}
-
- It's processing
- It's a kind of C



NA ARDUINO SKETCH - SETUP

```
pinMode(ledPin, Output);  
// set the pin `ledPin' as an  
output
```

```
serial.Begin(9600);  
// talk to the computer at  
// 9600 baud rate
```

- There's not much more than this



NA ARDUINO SKETCH – LOOP FUNCTIONS

Input and output functions

```
digitalWrite(8,HIGH);  
// turns on digital pin 8  
  
val = digitalRead(7);  
// reads pin 7 into val  
  
val = analogRead(0);  
// reads analog input 0 into val (0..1024)  
  
analogWrite(9,128);  
// Dim an LED on pin 9 to 50%  
  
time = pulsein(7,HIGH);  
// measures the time the next  
// pulse stays high
```

Time functions

```
duration = millis()-lastTime;  
// computes time elapsed since  
"lastTime"  
  
delay(500);  
// stops the program for half a second  
  
delayMicroseconds(1000);  
// waits for 1 millisecond
```

/



NA ARDUINO SKETCH – LOOP FUNCTIONS

Math functions

```
val = min(10,20);  
// val is now 10
```

```
val = max(10,20);  
// val is now 20
```

```
val = abs(-5);  
// val is now 5
```

```
val = constrain(analogRead(0), 0, 255);  
// reject values bigger than 255
```

```
val = map(analogRead(0),0,1023,100, 200);  
// maps the value of analog 0  
//to a value between 100 and 200
```

(Cont.)

```
double x = pow(y, 32);  
// sets x to y raised to the 32nd power  
double a = sqrt(1138);  
// approximately 33.73425674438
```

```
double sine = sin(2);  
// approximately 0.90929737091  
// aslo for cosine and tangent
```

```
randomSeed(analogRead(5));  
// randomize using noise from pin 5
```

```
long randnum = random(0, 100);  
// a number between 0 and 99  
long randnum = random(11);  
// a number between 0 and 10
```



NA ARDUINO SKETCH – LOOP FUNCTIONS

Serial communication functions

```
Serial.begin(9600);  
// usually no more than 115,200 bps.
```

```
Serial.print(75);  
// Prints "75"  
Serial.print(75, DEC);  
// The same as above.  
Serial.print(75, HEX);  
// "4B" (75 in hexadecimal)  
Serial.print(75, OCT);  
// "113" (75 in octal)  
Serial.print(75, BIN);  
// "1001011" (75 in binary)
```

(Cont.)

```
Serial.println(75);  
// Prints "75\r\n"  
Serial.println(75, DEC);  
// The same as above.  
Serial.println(75, HEX);  
// "4B\r\n"  
Serial.println(75, OCT);  
// "113\r\n"  
Serial.println(75, BIN);  
// "1001011\r\n"  
  
int count = Serial.available(); // bytes  
ready  
int data = Serial.read(); // get one byte  
Serial.flush(); // cleans the input buffer
```



// EXAMPLE 01 : BLINKING LED

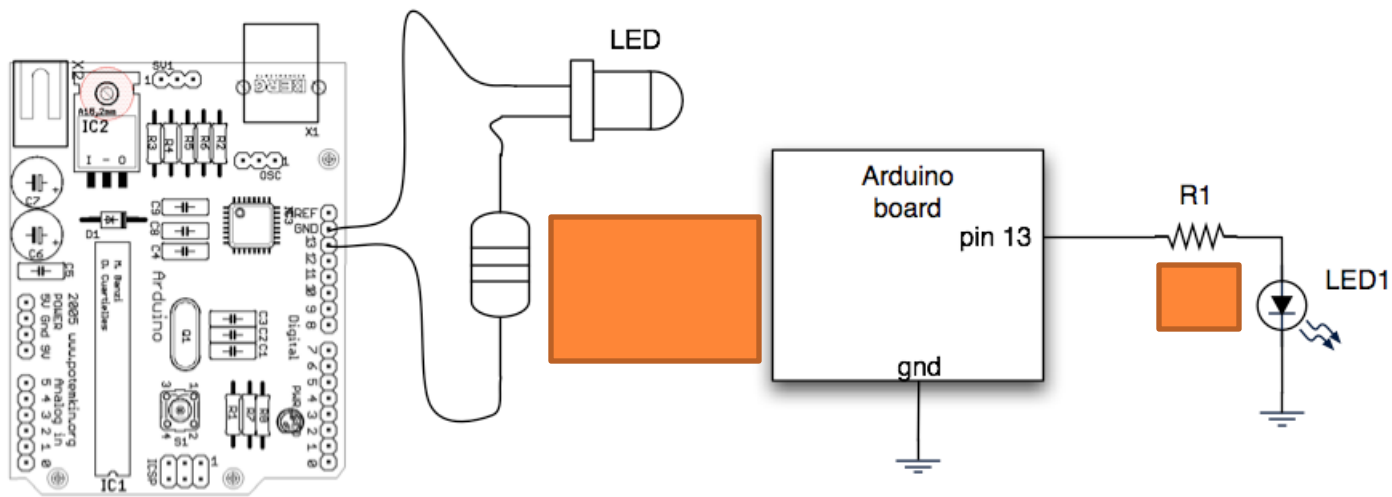
```
const int LED = 13;           // LED connected to
                               // digital pin 13

void setup()
{
    pinMode(LED, OUTPUT);     // sets the digital
                               // pin as output
}

void loop()
{
    digitalWrite(LED, HIGH);  // turns the LED on
    delay(1000);              // waits for a second
    digitalWrite(LED, LOW);   // turns the LED off
    delay(1000);              // waits for a second
}
```



ASSIGNMENT 1: DIGITAL OUTPUT



CAUTION WITH SPECS

ARDUINO specs

- I/O
 - they operate at 5 volts
 - provide or receive a maximum of 40 mA
- DC Current
 - 3.3V Pin max 50 mA
- +5 V is out
- All at
 - <http://arduino.cc/en/Main/arduinoBoardUno>

LED specs

Colour	I _F max.	V _F typ.	V _F max.	V _R max.	Luminous intensity
Red	30mA	1.7V	2.1V	5V	5mcd @ 10mA
Bright red	30mA	2.0V	2.5V	5V	80mcd @ 10mA
Yellow	30mA	2.1V	2.5V	5V	32mcd @ 10mA
Green	25mA	2.2V	2.5V	5V	32mcd @ 10mA
Blue	30mA	4.5V	5.5V	5V	60mcd @ 20mA
Red	30mA	1.85V	2.5V	5V	500mcd @ 20mA
Red	30mA	1.7V	2.0V	5V	5mcd @ 2mA



ASSIGNMENT 1: THE CODE

```
int ledPin = 13;           // LED connected to digital pin 13

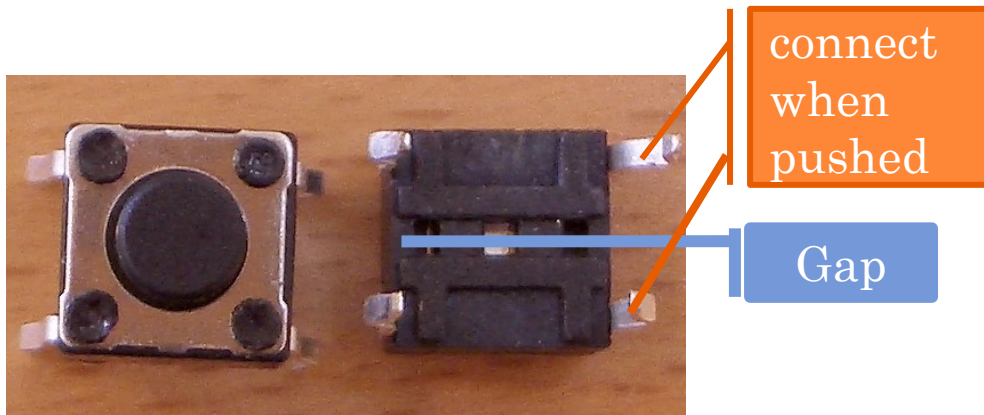
void setup()
{
  pinMode(ledPin, OUTPUT); // sets the digital pin as output
}

void loop()
{
  digitalWrite(ledPin, HIGH); // sets the LED on
  delay(1000);                // waits for a second
  digitalWrite(ledPin, LOW);  // sets the LED off
  delay(1000);                // waits for a second
}
```



ASSIGNMENT 2: SWITCHES

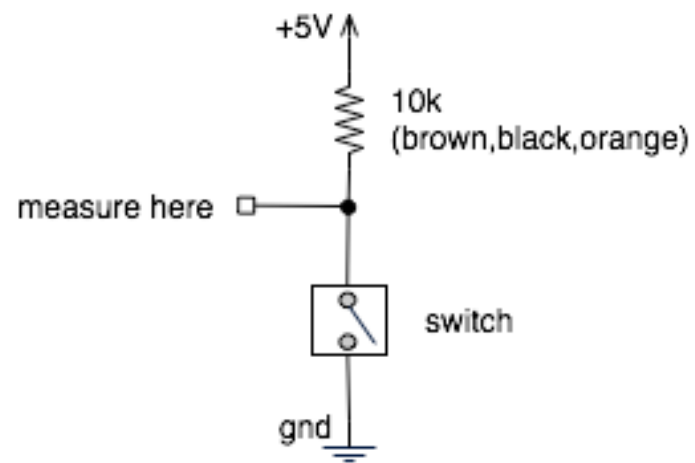
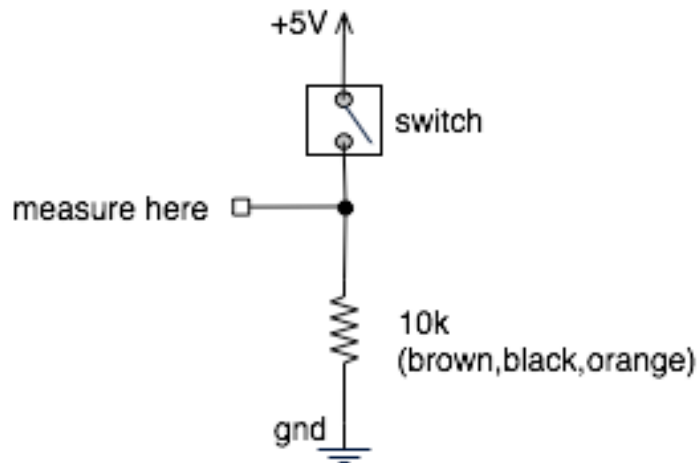
- Switches make or break a connection
- Arduino needs a voltage
 - Specifically, a “HIGH” (5 volts)
 - or a “LOW” (0 volts)



- Pressing the button, “closes the gap”
- How do you go from make/break to high/low?

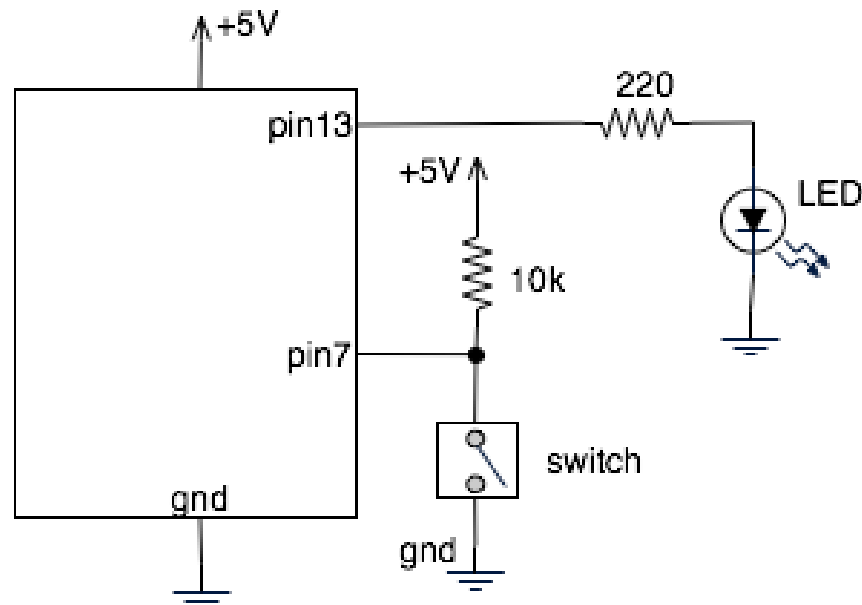


PULL DOWN/UP RESISTORS



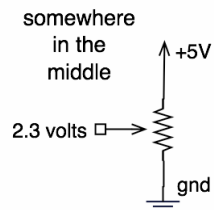
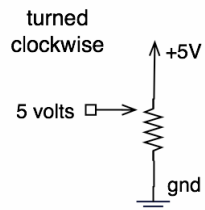
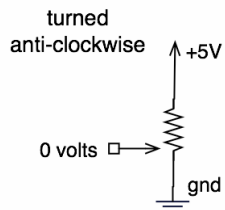
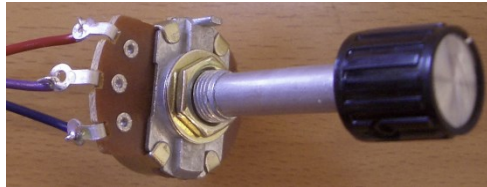
ASSIGNMENT 2: DIGITAL INPUT & OUTPUT

- Add switch circuit to any digital input (except pin 13)
- For output, use either existing pin 13 LED or wire up your own



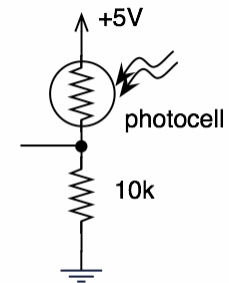
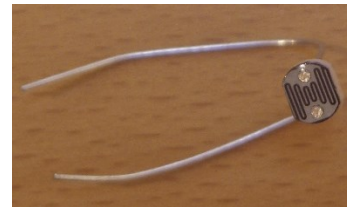
ASSIGNMENT 3: ANALOGUE INPUT

The potentiometer



The Photocell

- A variable resistor
- Brighter light == lower resistance
- Photocells you have range approx. 0-10k



`analogRead ()`

- Resolution is 10-bit (1024 states)
- In other words, $5/1024 = 4.8$ mV smallest voltage change you can measure



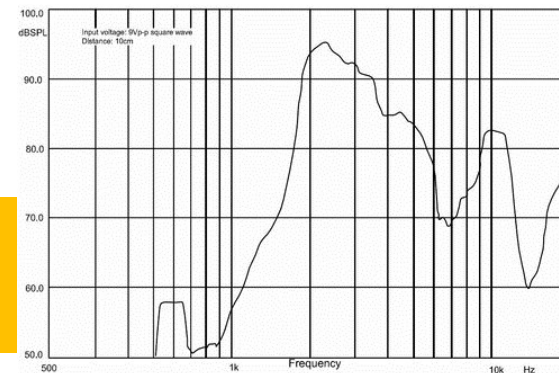
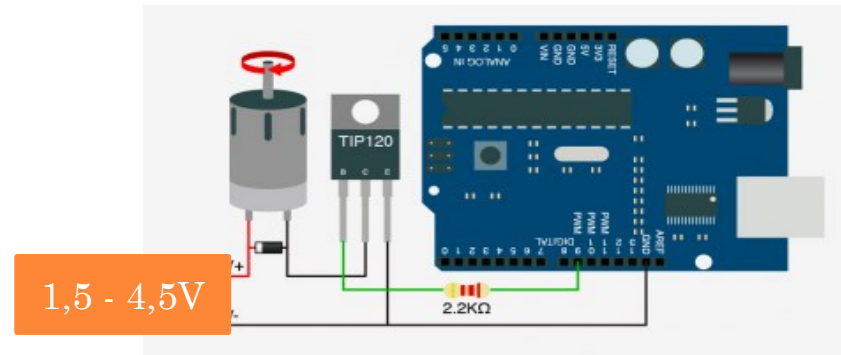
ASSIGNMENT 3: ANALOGUE STUFF

○ Input

- Use the potentiometer (e.g. to regulate colour)
- Use the light sensor (e.g. to regulate intensity)

○ Output

- Use the RGB LED
- Use a motor (specs!!!)
 - Motor INM-0411
 - 1,5V to 4,5V
 - Load current: 0.35A
 - Arduino UNO
 - I/O 40mA
 - <http://bildr.org/2011/03/high-power-control-with-arduino-and-tip120/>
- Use a buzzer (specs!!!)
 - 1 - 30V
 - low current draw (5 mA at 9V)



`analogWrite()`

- Resolution is 8-bit (256 states)
- Available in specific Pins



ASSIGNMENT 4: COMMUNICATION BASICS

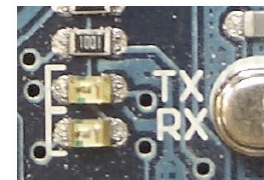
- Talking to other devices uses the “Serial” commands

- Serial.begin() – prepare to use serial
- Serial.print() – send data to computer
- Serial.read() – read data from computer

```
void setup() {  
    Serial.begin(9600);  
}  
  
void loop()  
{  
    Serial.print("Light the LED [y/n]? ");  
    while (Serial.available() == 0);  
  
    data = Serial.read();  
    if (data == 'y')  
        digitalWrite(led, HIGH);  
    else  
        digitalWrite(led, LOW);  
  
    tosend[0] = data;  
    Serial.println(tosend);  
}
```

- TX/RX LEDs

- TX – sending to PC
- RX – receiving from PC
- Used when programming or communicating



ASSIGNMENT 5: COMMUNICATION C#

```
using System;
using System.IO.Ports;

public partial class MainWindow : Window {
    SerialPort arduino;

    public MainWindow() {
        InitializeComponent();
        _arduino = new SerialPort("COM5", 9600);
        _arduino.DataReceived += _arduino_DataReceived;
        try {
            _arduino.Open();
        } catch {
            MessageBox.Show("Could not connect");
        }
    }
    void _arduino_DataReceived(object sender, SerialDataReceivedEventArgs e) {
        try {
            string data = _arduino.ReadLine();
            this.Dispatcher.Invoke(new Action() => { this._label.Content = data; });
        } catch (Exception ex) {
            MessageBox.Show("Could not read data" + ex.StackTrace);
        }
    }
    private void myAppChecked(object sender, RoutedEventArgs e)
    {
        CheckBox chk = e.Source as CheckBox;
        if ((bool)chk.IsChecked)
            _arduino.Write("y");
        else
            _arduino.Write("n");
    }
}
```

ARDUINO

```
void loop()
{
    Serial.print("Light the LED [y/n]? ");
    Serial.println(ledstatus);
    while (Serial.available() == 0);

    data = Serial.read();
    if (data == 'y')
        digitalWrite(led, HIGH);
    else
        digitalWrite(led, LOW);

    ledstatus[0] = data;
}
```

